



## Author Correction: 3D nanofabricated soft microrobots with super-compliant picoforce springs as onboard sensors and actuators

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In the version of the article initially published, in Fig. 4c, the units of the approach and transport velocities were erroneously listed as  $\mu\text{m}/\text{min}$  instead of  $\mu\text{m s}^{-1}$ . This has now been corrected in the HTML and PDF versions of the article.

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